

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	(laser near robot) and ((distance or height) near sensor) and acceleration and (backlash or play or jerk or rebound or whip or (inertia near force))	USOCR	OR	ON	2005/08/29 14:26
L2	0	(laser near robot) and ((distance or height) near sensor) and acceleration	USOCR	OR	ON	2005/08/29 14:25
L3	0	(laser near robot) and (distance or height) and acceleration and (backlash or play or jerk or rebound or whip or (inertia near force))	USOCR	OR	ON	2005/08/29 14:26
L4	0	(laser near robot) and ((distance or height) near sensor) and (backlash or play or jerk or rebound or whip or (inertia near force))	USOCR	OR	ON	2005/08/29 14:26
L5	0	(laser near robot) and (distance or height) and acceleration and (backlash or play or jerk or rebound or whip or (inertia near force))	USOCR	OR	ON	2005/08/29 14:26
L6	0	(laser near robot) and (distance or height)	USOCR	OR	ON	2005/08/29 14:26
L7	1	(laser near robot) and ((distance or height) near sensor) and acceleration and (backlash or play or jerk or rebound or whip or (inertia near force))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/29 14:27
L8	4	(laser near robot) and ((distance or height) near sensor) and (backlash or play or jerk or rebound or whip or (inertia near force))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/29 14:27
L9	3	(laser near robot) and ((distance or height) near sensor) and acceleration	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/29 14:28
L10	24	(laser near robot) and ((distance or height) near sensor)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/29 14:34
L11	10	(laser near robot) and ((distance or height) same sensor) and (laser near (machine or machining or machined))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/29 14:34